ABSTRACT OF THE DISCLOSURE:

The invention describes a stair-climbing hand truck (1) with two casters (3) held in a chassis (2) and with a supporting foot (5) which is arranged as a two-arm lever and is guided with its end opposite of the lower touchdown end over the lifting height along a supporting foot guide means (7) and is connected with a crank mechanism (13) between the touchdown end and the upper guided end. In order to provide advantageous sequences of movement it is proposed that the crank mechanism (13) acts upon a connecting rod (9) linked to the supporting foot (5) and that a connecting rod guide means (10) which extends transversally to the supporting foot guide means (7) is provided for the end of the connecting rod (9) which is opposite of the supporting foot (5)

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(Fig. 1)